

# PT5CN

## CANbus • SAE J1939 Output Signal

Absolute Linear Position to 250 inches (6350 mm)

Hard Anodized Aluminum Enclosure

High Cycle Applications

IP67 • NEMA 6 Protection

### GENERAL

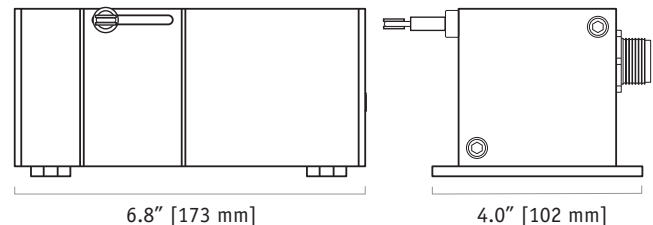
Full Stroke Ranges	0-10 to 0-250 inches
Electrical Interface	CANbus SAE J1939
Protocol	Proprietary B
Accuracy	$\pm 0.25\%$ to $\pm 0.10\%$ full stroke
Repeatability	$\pm 0.02\%$ full stroke
Resolution	$\pm 0.003\%$ full stroke
Measuring Cable	stainless steel or thermoplastic
Enclosure Material	hard anodized aluminum
Sensor	plastic-hybrid precision potentiometer
Potentiometer Cycle Life	see ordering information
Maximum Retraction Acceleration	see ordering information
Weight	5 lbs. max.

### ELECTRICAL

Input Voltage	7 - 18 VDC
Input Current	60 mA max.
Baud Rate	125K, 250K, or 500K via DIP switches
Update Rate	10 ms. (20 ms. available— <i>contact factory</i> )

### ENVIRONMENTAL

Environmental Suitability	NEMA 4/6, IP 65/67
Operating Temperature	-40° to 185°F (-40° to 85°C)
Vibration	up to 10 g to 2000 Hz maximum



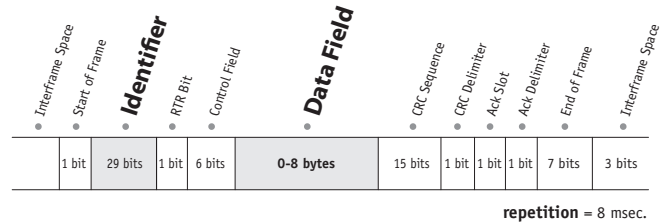
The PT5CN cable extension position transducer communicates linear position via the CANbus SAE J1939 interface providing a precision position feedback to your PLC. The PT5DN is offered in full stroke ranges up to 250 inches and a thermoplastic measuring cable for high cycle and rugged applications.

Because the PT5CN uses a potentiometer as its sensing element, the position signal is "absolute" and does not have to be reset to a "home" position upon startup.

### Output Signal:



# I/O Format and Settings



## • Identifier

	Message Priority					Future Use		J1939 Reference Proprietary B								Data Field Type*								Not Used		Node ID**							
Example –	1	0	0	0	0	1	1	1	1	1	1	1	1	0	1	0	1	0	0	1	1	0	0	1	1	1	1	1	1	1			
Identifier Bit No. –	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0				
Hex Value –	0					F					F				5				3				3		F								

\*Sensor field data can be factory set to customer specific value.

\*\*Customer defined, set via Dips 1-6. Bit values shown for example only, see **Address Setting** below.

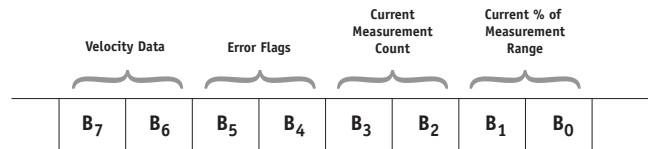
## • Data Field

**B<sub>0</sub>** = LSB current % of measurement range byte  
**B<sub>1</sub>** = MSB current % of measurement range byte

**B<sub>2</sub>** = LSB current measurement count byte  
**B<sub>3</sub>** = MSB current measurement count byte

**B<sub>4</sub>** = error flag  
**B<sub>5</sub>** = error flag

**B<sub>6</sub>** = LSB velocity data byte  
**B<sub>7</sub>** = MSB velocity data byte



B <sub>7</sub>	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	B <sub>3</sub>	B <sub>2</sub>	B <sub>1</sub>	B <sub>0</sub>
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### Current Measurement Count

The **Current Measurement Count (CMC)** is the output data that indicates the present position of the measuring cable. The CMC is a 16-bit value that occupies bytes **B<sub>2</sub>** and **B<sub>3</sub>** of the data field. **B<sub>2</sub>** is the **LSB** (least significant byte) and **B<sub>3</sub>** is the **MSB** (most significant byte).

The **CMC** starts at **0x0000** with the measuring cable fully retracted and continues upward to the end of the stroke range stopping at **0xFFFF**. This holds true for all ranges.

### Converting CMC to Linear Measurement

To convert the current measurement count to inches or millimeters, simply divide the count by 65,535 (total counts over the range) and then multiply that value by the full stroke range:

$$\left( \frac{\text{current measurement count}}{65,535} \right) \times \text{full stroke range}$$

Sample Conversion:

If the full stroke range is **30 inches** and the current position is **0x0FF2** (4082 Decimal) then,

$$\left( \frac{4082}{65,535} \right) \times 30.00 \text{ inches} = 1.87 \text{ inches}$$

If the full stroke range is **625 mm** and the current position is **0x0FF2** (4082 Decimal) then,

$$\left( \frac{4082}{65,535} \right) \times 625 \text{ mm} = 39 \text{ mm}$$

B <sub>7</sub>	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	B <sub>3</sub>	B <sub>2</sub>	B <sub>1</sub>	B <sub>0</sub>
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### Current % of Measurement Range

The **Current % of Measurement Range** is a 2-byte value that expresses the current linear position as a percentage of the entire full stroke range. Resolution is **.1 %** of the full stroke measurement range.

This value starts at **0x0000** at the beginning of the stroke and ends at **0x03E8**.

Example:

Hex	Decimal	Percent
0000	0000	0.0%
0001	0001	0.1%
0002	0002	0.2%
...	...	...
03E8	1000	100.0%

B <sub>7</sub>	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	B <sub>3</sub>	B <sub>2</sub>	B <sub>1</sub>	B <sub>0</sub>
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### Error Flags

**0x55** (yellow LED on controller board) indicates that the sensor has begun to travel beyond the calibrated range of the internal position potentiometer.

**0xAA** (red LED on controller board) indicates that the sensor has moved well beyond the calibrated range of the internal position potentiometer.

If either error flag occurs within the full stroke range of the sensor, the unit should be returned to the factory for repair and recalibration.

B <sub>7</sub>	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	B <sub>3</sub>	B <sub>2</sub>	B <sub>1</sub>	B <sub>0</sub>
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### Velocity

Data in bytes **B<sub>7</sub>** - **B<sub>6</sub>** is the change in the **CMC** (current measurement count) over a 100 msec time period. This data can then be used to calculate velocity in a post processing operation.

B <sub>7</sub> - B <sub>6</sub> HEX (Decimal)	$\frac{\text{max "reverse" velocity}}{\text{max "forward" velocity}}$	Velocity (cts./100 msec.)
0x0000 (0)		- 32767 counts
0x7FFF (32767)		"0" counts (no change)
0xFFFF (65535)		32767 counts

### Velocity Calculation

$$\left( \frac{\text{count change} - 32767}{.1 \text{ sec. time period}} \right) \times \left( \frac{\text{full stroke range}}{65,535} \right)$$

#### Sample Calculations

Cable Extension (positive direction):

**B<sub>7</sub>-B<sub>6</sub> = 0x89C6** (43462 Dec), **full stroke = 60 in.**

$$\left( \frac{35270 - 32767}{.1 \text{ sec}} \right) \times \left( \frac{60 \text{ in.}}{65,535} \right) = 22.92 \text{ in. / sec.}$$

Cable Retraction (negative direction):

**B<sub>7</sub>-B<sub>6</sub> = 0x61A8** (25000 Dec), **full stroke = 60 in.**

$$\left( \frac{25000 - 32767}{.1 \text{ sec}} \right) \times \left( \frac{60 \text{ in.}}{65,535} \right) = -71.11 \text{ in. / sec.}$$

## Setting the Address (Node ID) and Baud Rate

### Address Setting (Node ID)

The Address Setting (Node ID) is set via 6 switches located on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

The DIP switch settings are binary starting with switch number 1 (=  $2^0$ ) and ending with switch number 6 (=  $2^5$ ).

DIP-1 ( $2^0$ )	DIP-2 ( $2^1$ )	DIP-3 ( $2^2$ )	DIP-4 ( $2^3$ )	DIP-5 ( $2^4$ )	DIP-6 ( $2^5$ )	address (decimal)
0	0	0	0	0	0	0
1	0	0	0	0	0	1
0	1	0	0	0	0	2
...	...	...	...	...	...	...
1	1	1	1	1	1	63

### Baud Rate

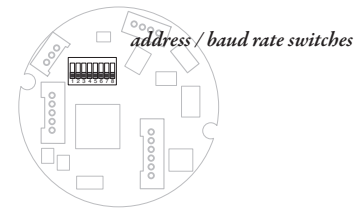
The transmission baud rate may be either factory preset at the time of order or set manually at the time of installation.

The baud rate can be set using switches 7 & 8 on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

DIP-7	DIP-8	baud rate
0	0	125k
1	0	250k
0	1	500k
1	1	125k

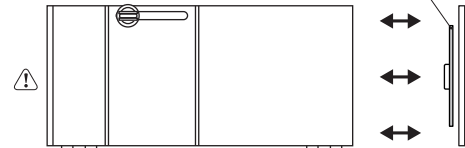


### CANBus Controller Board



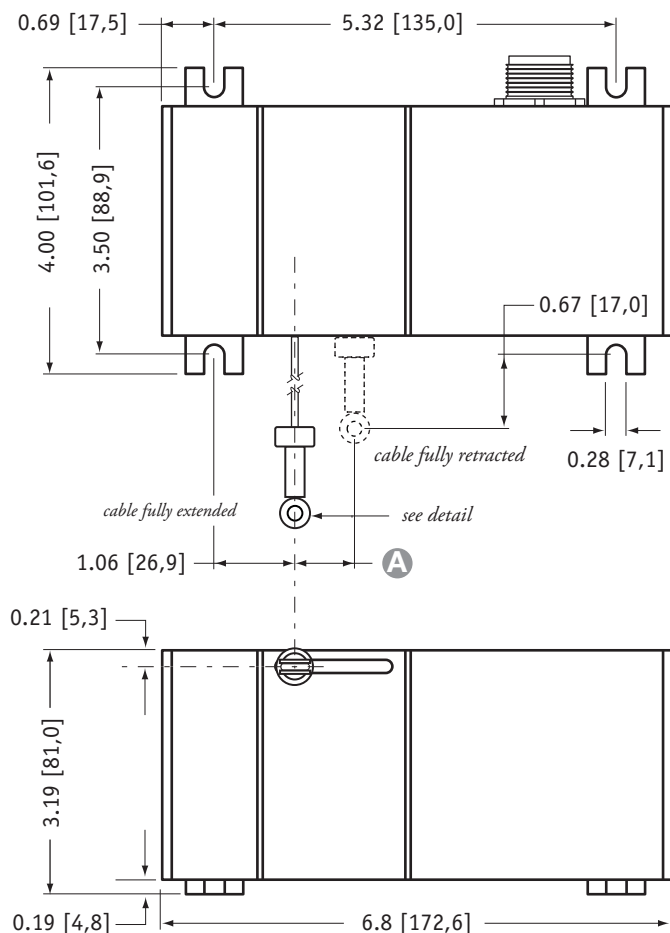
#### internal dip switches & controller board

to gain access to the controller board, remove four Allen-Head Screws and remove end cover bracket.

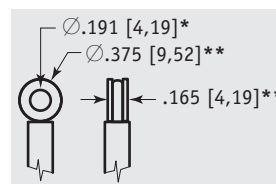


**Caution! Do Not Remove Spring-Side End Cover**  
removing spring-side end cover could cause spring to become unseated and permanently damaged.

### Outline Drawing:

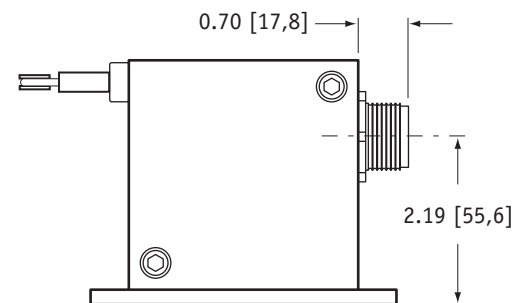


#### eyelet detail



#### A DIMENSION (inches[mm])

RANGE	N34	S47 & V62
	measuring cable	measuring cable
10	0.05 [1,2]	0.08 [2,0]
15	0.07 [1,8]	0.12 [3,0]
20	0.09 [2,4]	0.16 [3,9]
30	0.14 [3,5]	0.23 [5,9]
40	0.19 [4,7]	0.31 [7,9]
50	0.23 [5,9]	0.39 [9,9]
60	0.28 [7,0]	0.47 [11,8]
80	0.37 [9,4]	0.62 [15,8]
100	0.46 [11,7]	0.78 [19,7]
125	0.58 [14,7]	0.97 [24,7]
150	0.69 [17,6]	1.16 [29,6]
200	0.92 [23,5]	n/a
250	1.16 [29,3]	n/a



DIMENSIONS ARE IN INCHES [MM]  
tolerances are 0.03 IN. [0.5 MM] unless otherwise noted.

\* tolerance = +.005 -.001 [+13 -.03]  
\*\* tolerance = +.005 -.005 [+13 -.13]

## Ordering Information:

### Model Number:

**PT5CN** - - - - **J** - - - -  
*order code:* **R A B C D E F**

Sample Model Number:

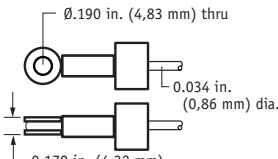
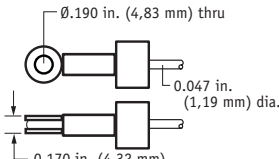
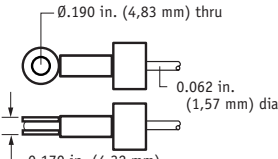
**PT5CN - 50 - S47 - FR - J - 500 - 32 - SC5**

<b>R</b> range:	50 inches
<b>A</b> measuring cable:	.047 stainless steel
<b>B</b> measuring cable exit:	front
<b>C</b> interface:	CANbus SAE J1939
<b>D</b> baud rate:	500 k bits/sec.
<b>E</b> node ID:	32 decimal
<b>F</b> electrical connection:	5-meter cordset with straight plug

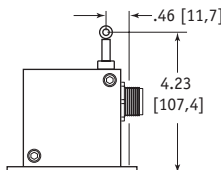
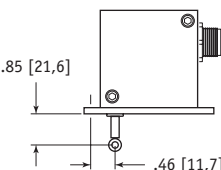
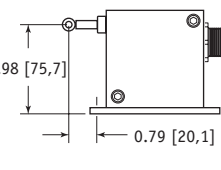
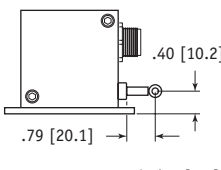
### Full Stroke Range:

<b>® order code:</b>	<b>10</b>	<b>15</b>	<b>20</b>	<b>25</b>	<b>30</b>	<b>40</b>	<b>50</b>	<b>60</b>	<b>80</b>	<b>100</b>	<b>125</b>	<b>150</b>	<b>200</b>	<b>250</b>
full stroke range, min:	10 in.	15 in.	20 in.	25 in.	30 in.	40 in.	50 in.	60 in.	80 in.	100 in.	125 in.	150 in.	200 in.	250 in.
accuracy (± of f.s.):	.75%	.6%	.5%	.5%	.5%	.3%	.3%	.25%	.25%	.25%	.25%	.18%	.18%	.18%
repeatability (± of f.s.):	.1%	.1%	.05%	.05%	.05%	.05%	.05%	.02%	.02%	.02%	.02%	.02%	.02%	.02%
potentiometer cycle life:	2,500,000 cycles						500,000 cycles						250,000 cycles	
cable tension (20%):	41 ounces												21 ounces	
max. cable velocity/acceleration:	300 in./sec • 5 g												120 in./sec • 2 g	

### Measuring Cable:

<b>A</b> <i>order code:</i>	<b>N34</b>	<b>S47</b>	<b>V62</b>
	.034 nylon-coated stainless steel available in all ranges	.047 stainless steel all ranges up to 150 inches	.062 thermoplastic all ranges up to 150 inches
			

### Cable Exit:

<b>B</b> <i>order code:</i>	<b>UP</b>	<b>DN</b>	<b>FR</b>	<b>BK</b>
	up	down	front	back
				
	inches [mm]			

### Baud Rate:

<b>D</b> <i>order code:</i>	<b>125</b>	<b>250</b>	<b>500</b>
	125 kbaud	250 kbaud	500 kbaud

### Node ID:

<b>E</b> <i>order code:</i>	<b>0</b>	<b>1</b>	<b>2</b>	<b>...</b>	<b>62</b>	<b>63</b>
	select address (0 - 63 Decimal)					

