PT8232 Heavy Industrial • RS232

Absolute Linear Position to 60 inches (1524 mm) Aluminum or Stainless Steel Enclosure Options VLS Option To Prevent Free-Release Damage IP67 • NEMA6 Protection

GENERAL

Full Stroke Ranges		0-2 to 0-60 inches			
Electrical Interface		RS232			
Format		HEX			
Accuracy	± 0	.25% to \pm 0.10% full stroke			
Repeatability		\pm 0.02% full stroke			
Resolution		± 0.003% full stroke			
Measuring Cable	less steel or thermoplastic				
Enclosure Material	powder-painted a	d aluminum or stainless steel			
Sensor	plastic-hybri	d precision potentiometer			
Potentiometer Cycle Life		see ordering information			
Maximum Retraction Accel	see ordering information				
Weight, Aluminum (Stainle	ss Steel) Enclosure	3 lbs. (6 lbs.), max.			

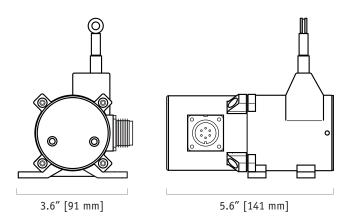
ELECTRICAL

Input Voltage	922 VDC
Input Current	40 mA
Baud Rate	9600 (selectable to 38.4K)
Update Rate	32 msec

ENVIRONMENTAL

Environmental Suitability	NEMA 4X/6, IP 67
Operating Temperature	-40° to 200°F (-40° to 90°C)
Vibration	up to 10 g's to 2000 Hz maximum





The PT8232 delivers position feedback via RS232 serial communication to your data acquisition or controller system. The PT8232 sends a raw 16-bit count from 0000H to FFFFH. Additionally this device can be set to continuously send data or send data only when polled.

As the internal position sensing element is a precision potentiometer, this transducer maintains current accurate position even during power loss and does not need to be reset to a "home" position.

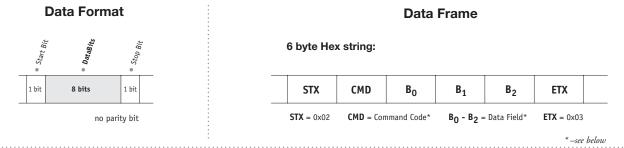
Output Signal:



20630 Plummer Street • Chatsworth, CA 91311 tel: 800.423.5483 • +1.818.701.2750 • fax: +1.818.701.2799



I/O Format:



Important! All communications to/from the transducer are in HEX!

User Commands:

User Command

Sensor Response

Description	<cmd></cmd>	< B ₀ >	< B ₁ >	<b2></b2>	<cmd></cmd>	< B ₀ >	<b1></b1>	<b2></b2>
Get Sensor Info	0x05	0x00	0x00	0x00	0x05	version ⁽⁴⁾	date ⁽⁵⁾	date ⁽⁵⁾
Get Serial Number	0x15	0x00	0x00	0x00	0x15	se	rial number ⁽	3)
Start Continuous Data	0x25	0x00	0x00	0x00	0x25	0x00	0x00	0x00
Stop Continuous Data	0x35	0x00	0x00	0x00	0x35	0x00	0x00	0x00
Get Position Data	0x45	0x00	0x00	0x00	0x45	$CMC^{(1)}$	$CMC^{(1)}$	status ⁽²⁾

⁽¹⁾CMC - Current Measurement Count (Position)

The ${\bf C}{\bf u}{\bf r}{\bf r}{\bf e}{\bf n}$ Measurement ${\bf C}{\bf o}{\bf u}{\bf n}{\bf t}$ (CMC) is the output data that indicates the present position of the measuring cable.

The CMC is a 16-bit value that occupies the first two bytes (B_0 and B_1) of the data field. B_0 is the MSB (most significant byte) and B_1 is the LSB (least significant byte).

The CMC starts at 0000H with the measuring cable fully retracted and continues upward to the end of the stroke range stopping at FFFFH. This holds true for all ranges.

(2)Status

The status byte is used as a flag to indicate the validity of the position signal that the internal electronics receives from the potentiometer.

Flags are as follows:

0x00 = GREEN, 0x55 = YELLOW, 0xAA = RED

A "green" flag shows everything OK. A "yellow" or "red" flag indicates that the sensor has either been extended beyond its range or that there is a problem with the potentiometer.

⁽³⁾Serial Number

Each sensor has it's own unique serial number. This information can be retrieved by sending the sensor the "Get Serial Number" command.

The serial number is a 3 byte value from which ranges from 0 to 9999999 (decimal).

(4) Version

This is a single byte value (0-255 decimal) which indicates the currently installed firmware version of the sensor.

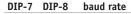
(5) Date

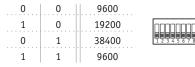
This is a 2 byte value showing the date of currently installed firmware. This value ranges from 01011 - 12319 (decimal). Format is MMDDY. While the month and day are expressed as two digit numbers the year is expressed in a single digit only.

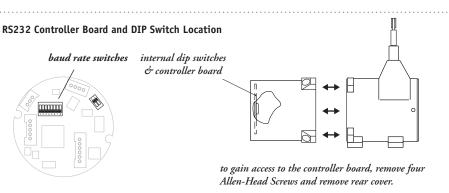
Example: 08054 = August 5, 2004



The baud rate can be set using switches **7** & **8** on the 8-pole DIP switch found on the rs232 controller board located inside the transducer.

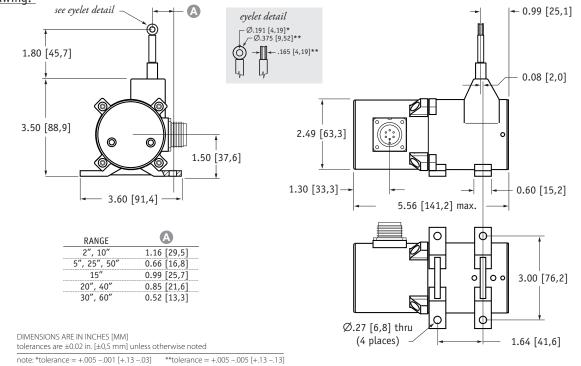






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Outline Drawing:



Ordering Information:



Sample Model Number:

D

T8232 -	50 -	AL -	N34 -	T1	-	CG - N	/16

ß	range:	200 inches
Ā	enclosure	aluminum
Ē	measuring cable:	.034 nylon-coated stainless
0	measuring cable tension:	standard
O	cable guide:	standard
• 🕒	electrical connection:	6-pin plastic connector

Full Stroke Range:

R order code;	2		5		10		15		20		25		30		40		50		60
full stroke range, min:	2 in.	:	5 in.	:	10 in.	:	15 in.	:	20 in.	:	25 in.	:	30 in.	:	40 in.	:	50	:	60
accuracy (% of f.s.):	0.25%	:	0.25%	:	0.15%	:	0.15%	:	0.15%		0.15%	÷	0.15%	:	0.10%	:	0.10%	÷	0.10%
potentiometer cycle life*:	2.5 x 10 ⁶		2.5 x 10 ⁶	:	5 x 10 ⁵	:	5 x 10 ⁵		5 x 10 ⁵		5 x 10 ⁵	:	5 x 10 ⁵		2.5 x 10 ⁵	÷	2.5 x 10 ⁵	:	2.5 x 10 ⁵

*-1 cycle is defined as the travel of the measuring cable from full retraction to full extension and back to full retraction

Enclosure Material:

A order code:	AL	SS	SS					
	powder-painted aluminur	n 303 stainl	316 stainless steel					
Measuring Cable:	N34	S47	S31	V62				
cable construction:	Ø.034-inch nylon-coated stainless steel rope	Ø.047-inch bare stainless steel rope	Ø.031-inch bare stainless steel rope	Ø.058-inch PVC jacketed vectra fiber rope				
available ranges:	all ranges	5, 15, 20, 25, 30-inch only	40, 50, 60-inch only	thru 30 inches only				
general use:	indoor	outdoor, debris, high temperature	outdoor, debris, high temperature	high voltage or magnetic field				

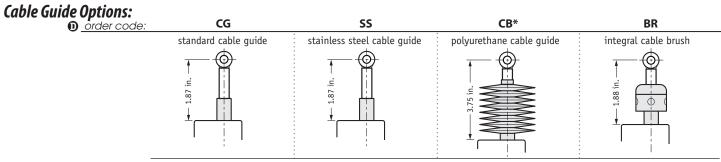
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Ordering Information (cont.):

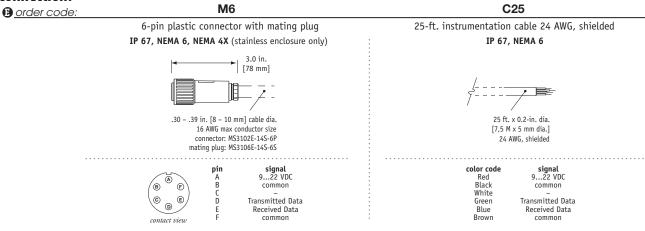
Measurina Cable Tension:

	C order code:	T1		T2		ТЗ
		standard tension	:	medium tension	:	high tension
	2, 10-inch:	39 oz.	*	65 oz.	*	116 oz.
full stroke ra		26 oz.	:	43 oz.		77 oz.
cable tens	.,	20 oz.		33 oz.	*	60 oz.
specificati	<i>ions</i> 5, 25, 50-inch:	16 oz.	*	26 oz.	*	47 oz.
	30, 60-inch:	13 oz.	*	22 oz.	0 6 7	40 oz.
	—					tension tolerance: \pm 50%
		maximum acceleration		maximum acceleration		maximum acceleration
	aluminum enclosure:	15 g	:	25 g		40 g
9	stainless steel enclosure:	6 g	•	12 g	:	18 g



*note: all ranges up to 25 inches only

Electrical Connection:



version: 7.0 last updated: May 29, 2014